

Sums of Squares, Gradient Ideals, and Optimization

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1 Introduction

2 An Example

Let $\mathbb{R}[X] := \mathbb{R}[x_1, \dots, x_n]$ and suppose $f, g_1, \dots, g_m \in \mathbb{R}[X]$.

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One idea for finding f^* is to use theorems from real algebraic geometry to reduce to a question involving sums of squares, implement this as a semidefinite program (SDP) and then solve numerically.

Let $\sum \mathbb{R}[X]^2$ denote the cone of sums of squares in $\mathbb{R}[X]$. For each integer k , let

$$V_k := \{p \in \mathbb{R}[X] \mid \deg p \leq k\}$$

and define the convex cones

$$M_k := \left\{ \sigma_0 + \sigma_1 g_1 + \cdots + \sigma_s g_s \mid \sigma_i \in \sum \mathbb{R}[X]^2, \sigma_i g_i \in V_k \right\}$$

$$P_k := \left\{ \sum_{\epsilon \in \{0,1\}^s} \sigma_\epsilon g_1^{\epsilon_1} \cdots g_s^{\epsilon_s} \in V_k \mid \sigma_\epsilon \in \sum \mathbb{R}[X]^2 \right\}$$

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Think of polynomials in M_k and P_k as “certifiably nonnegative” on S with “degree k sos certificates”.

Consider the following nonconvex quadratic optimization problem:

$$\begin{aligned} \min_{x \in \mathbb{R}^2} \quad & f(x) := x_1^2 + x_2^2 \\ \text{s.t.} \quad & g_1(x) := x_2^2 - 1 \geq 0 \\ & g_2(x) := x_1^2 - Mx_1x_2 - 1 \geq 0 \\ & g_3(x) := x_1^2 + Mx_1x_2 - 1 \geq 0 \end{aligned}$$

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It's easy to see that

$$f^* = \frac{1}{2}(M^2 + M\sqrt{M^2 + 4}) + 2$$

and the global minimizers are

$$\left(\pm \frac{1}{2}(M + \sqrt{M^2 + 4}), 1\right), \quad \left(\pm \frac{1}{2}(M + \sqrt{M^2 + 4}), -1\right).$$

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A straightforward argument shows that

$$\max\{\gamma \mid f - \gamma \in P\} = 2.$$

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Of course, the feasible set is noncompact in this case, hence Schmüdgen's Theorem (and the Lasserre method) does not apply.

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We implemented this approach using *SOSTOOLS* and found that the lower bounds obtained this way are still very bad. The bigger M is, the worse the bound.

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Using Macaulay 2 we check that the KKT ideal I_{KKT} in this case is radical.

Now let $q(x) =$

$$\begin{aligned} & \rho_1 \left(x_1^2 - \frac{1}{4}(M + \sqrt{M^2 + 4})^2 \right)^2 \lambda_1^2 ((x_1^2 + Mx_1x_2 - 1)\lambda_2^2 + (x_1^2 - Mx_1x_2 - 1)\lambda_3^2) \\ & \rho_2 \lambda_1^2 \left(\left(\frac{2\lambda_1}{2 + M^2} - 1 \right)^2 - \left(\frac{M^2}{M^2 + 4} \right)^2 \right)^2 (x_1^2 + Mx_1x_2 - 1) + \\ & \rho_3 (4\lambda_1\lambda_2)^2 (x_2^2 - 1) + \rho_4 (x_1^2 + Mx_1x_2 - 1)^2 (x_1^2 + Mx_1x_2 - 1)^2 (x_2^2 - 1) \\ & (\lambda_2(1 - 2\lambda_2))^2 \left(\rho_5 \left(\sqrt{M^2 + 1}x_1^2 + 1 \right) (x_2^2 - 1) + \rho_6 \left(\sqrt{M^2 + 1}x_1^2 - 1 \right) (x_2^2 - 1) \right) \\ & (\lambda_3(1 - 2\lambda_3))^2 \left(\rho_5 \left(\sqrt{M^2 + 1}x_1^2 + 1 \right) (x_2^2 - 1) + \rho_6 \left(\sqrt{M^2 + 1}x_1^2 - 1 \right) (x_2^2 - 1) \right) \end{aligned}$$

where the ρ_i are suitably chosen constants.

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where the ρ_i are suitably chosen constants. Then $q(x)$ is visibly in M_{KKT} and hence in P_{KKT} .

It can be shown, e.g. using Macaulay 2, that

$$f(x) - f^* \equiv q(x) \pmod{I_{5,KKT}}.$$

This implies that $f_5^* = f^*$, hence we converge to the exact solution for $N = 5$. Thus the KKT system plays a crucial role in this example.